

# THE NEXT GENERATION SPACE TELESCOPE

"Visiting a Time When Galaxies Were Young" -from HST and Beyond, AURA

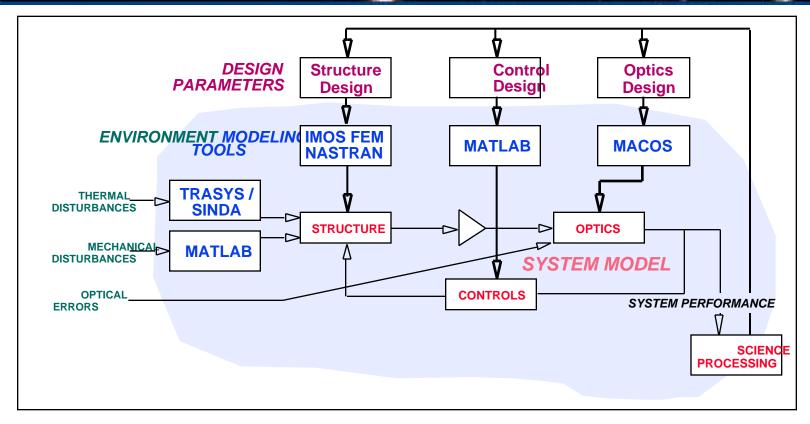
Integrated Modeling and Simulation Status

Gary Mosier
Goddard Space Flight Center

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# Integrated Modeling S/W Environment



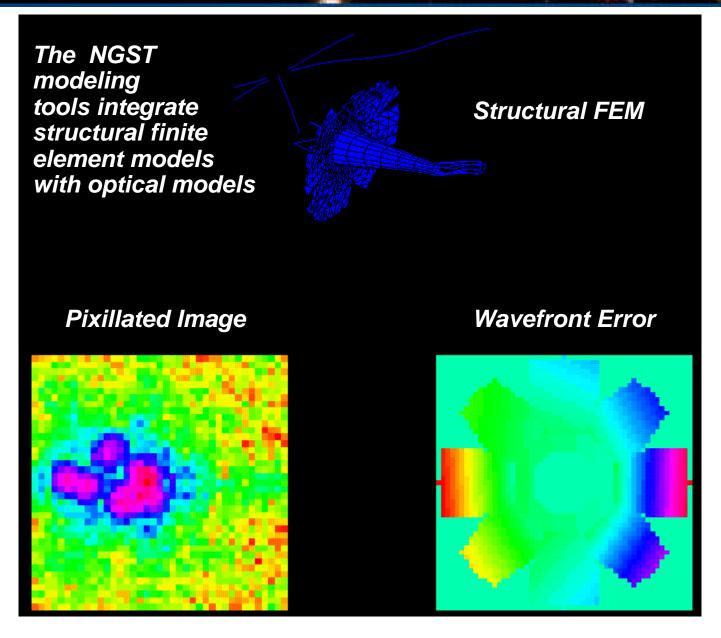
- Integrated performance models quantify thermal, structural, control, optics, detector and system issues in terms of science impact
  - Time-domain simulation, frequency-domain analysis, statistical analysis modes
  - Software testbed for attitude control and optical control/alignment algorithms
- Model and tool validation via experiments on testbeds, other instruments

# Modeling Highlights - S/W Environment NGST

- DCATT WFS/WFC models delivered to GSFC
- Added "Mode Movie" capability -- Matlab animations that show qualitative opto-mechanical interactions
- Upgraded simulation to Matlab 5.x/Simulink 2.x (objectoriented, many useful new features)
- Optimized versions of IMOS functions now in place (~20x run-time improvement)
- **NGST Integrated Modeling Environment was presented at** the annual Matlab Conference, this week in San Jose
- Demos of our modeling environment and capabilities were rehearsed, and rehearsed... but Wes **Huntress never showed!!!**

# **OptoMechanical Design Analysis**

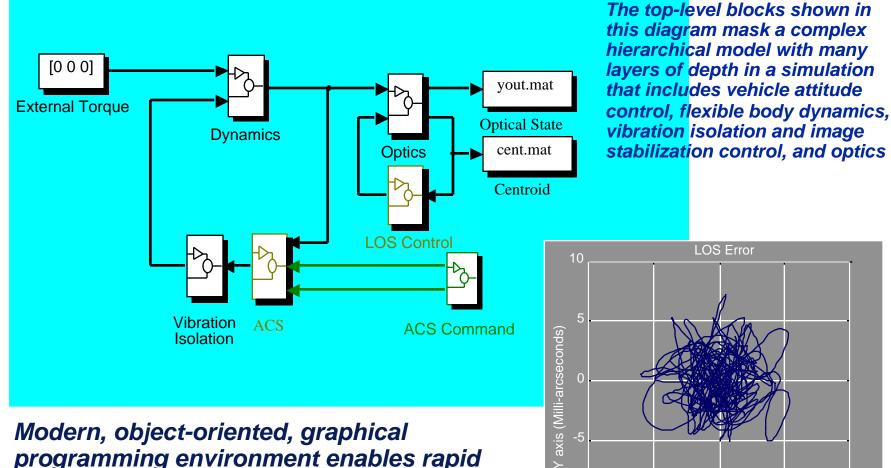




# Rapid Prototyping via Simulation

#### **NGST**

X Axis (milli-arcseconds)



programming environment enables rapid prototyping of high-fidelity simulations that can answer "what-if" questions and quickly cover vast parametric trade spaces



# NGST

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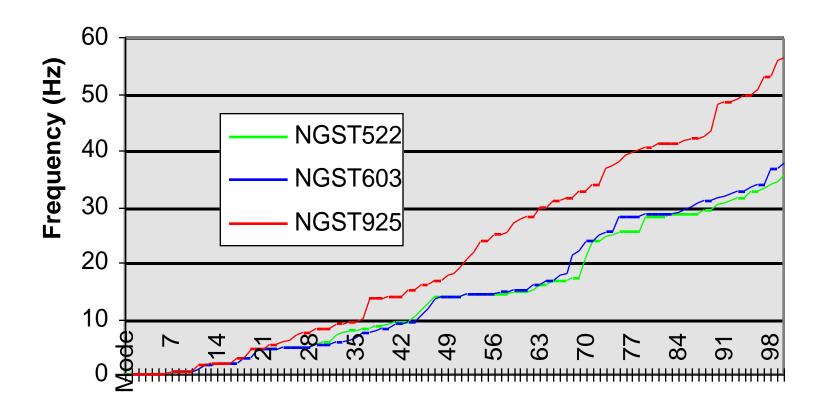


# OTA Design Trade Study, Part I

- A point-design trade study is being conducted to assess several different OTA designs
  - Be on GrEp PM segments (ngst522)
  - Be on Be PM segments (ngst603)
  - Be on Be PM segments w/ beefed-up SM truss (ngst925)
  - Be on GrEp PM segments w/ hexapod SM truss (not delivered)
- Primary metrics are LOS and RMS WFE
- Disturbance source is reaction wheels, using HST model scaled to NGST size requirements

Model	Mass (kg)	Inertia @ c.m. (kg-m^2)		
ngst522	2218.60	12249.00	-136.10	6858.80
		-136.10	25084.00	114.13
		6858.80	114.13	17847.00
ngst603	2166.70	11641.00	-133.57	6722.80
		-133.57	24559.00	112.08
		6722.80	112.08	17435.00
ngst925	2205.20	11730.00	-142.47	7206.20
		-142.47	27476.00	113.63
		7206.20	113.63	20268.00

... very little difference between the designs in this respect



... the 9/25 model is much stiffer, as a system

# Wheel-toCentroid Linear Model

- Linear Model used to generate LOS as a function of frequency
- ACS not included given its limited bandwidth
- Wheel disturbance is assumed to be a single white noise source
- Noise is scaled to yield the equivalent of 4 wheels phased to absolute worst case
- X and Y centroids RSS'ed to get LOS

# **Wheel Force/Torque Model**

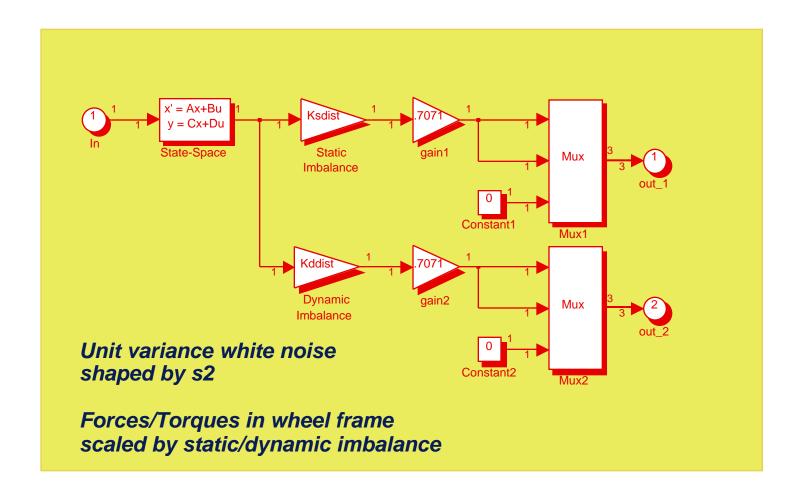
#### NGST

WHEEL FORCE IN BODY

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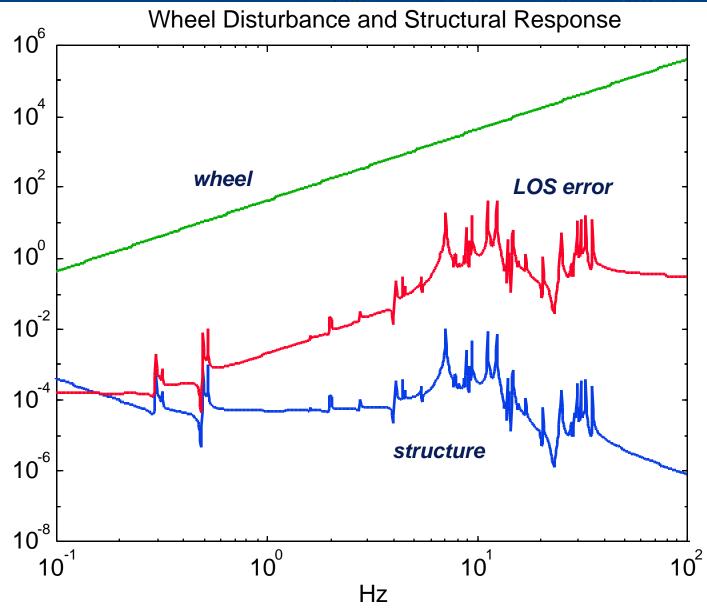
WHEEL TORQUE IN BODY

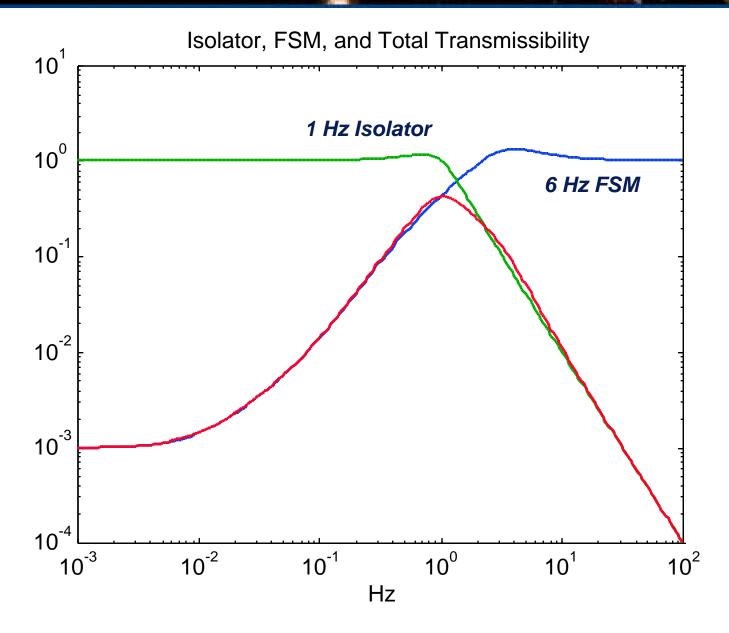
Coordinate transformation matrices modified via abs() to yeild RSS of 4 wheels





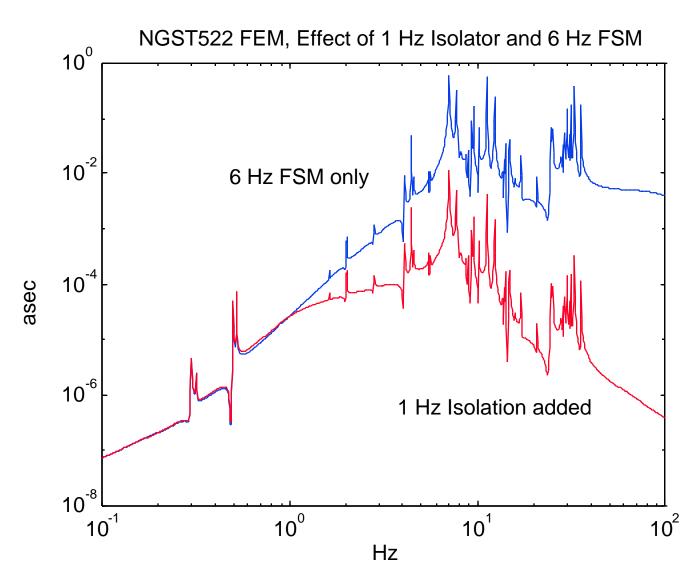
# **Effect of Wheels and FEM on LOS**



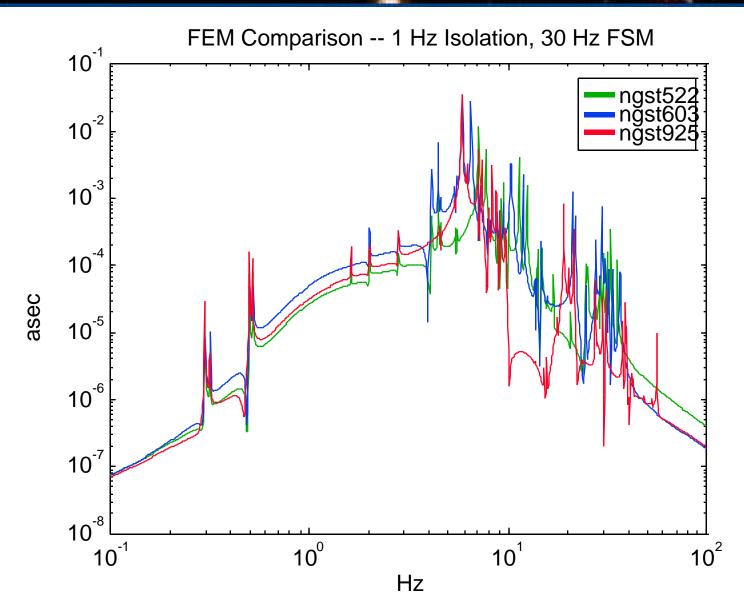




# **Net LOS Frequency Response**









### **OTA Trade Summary**

- Methodology needs refinement and additions
  - linear model too conservative by factor of at least 5, due to worst-case assumptions about wheel phasing
  - doesn't consider RMS WFE in the mode selection process
- Complete systems-level trade needs to include thermal analysis, diffraction analysis, etc.
- Preliminary results based on LOS, WFE, and mass properties leave little from which to choose

	LOS (SR)	LOS (SA)	LOS (LMA)	WFE (SR)	WFE (SA)
ngst522	8.5	2.7	11.7	0.123	0.023
ngst603	11.7	2.7	32.9	0.139	0.023
ngst925	9.8	2.7	35.5	0.118	0.023
LOS in milli-arcseconds			SR - simulation, raw		
WFE in microns			SA - simulation, attenuated		ted
simulations were 20 seconds			LMA - linear model, attenuated		



## Near-term/Long-term Modeling Goals

- Continue OTA design trades and other parametric studies
- Add hooks for variable modal damping; study damping issue
- Design a "real" vibration isolation subsystem, incorporate into models and simulation
- Refine and enhance ACS design and models (slew and acquisition modes, thruster models, fuel slosh model, magnetic bearing wheel model, etc.)
- Develop models for PM actuators to support NGST and DCATT analysis; enhance fidelity of WFS/WFC models accordingly
- Coordinate thermal modeling software environments
- Integrate multi-body dynamics code (DADS) with simulation (Simulink) for deployment analysis
- Attend IMOS workshop at JPL in January
- Continue to support LaRC NextGrade development efforts



### **A Vision For Future Capabilities**

#### NGST

Mission Ops Ground Stations

Physical or

**Prototypes** 

Virtual Reality

**SIMULATION** 

Real-time, hi-fidelity physics-based virtual prototype of NGST

Multiprocessor or multiworkstation w/ high-speed networking

Integrated 2D/3D visualization capabilities

**DESIGN** 

**ANALYSIS** 

Science Ops Ground Stations

Manufacturing and I&T Facilities

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Multidisciplinary front-end design and modeling tools and workstations, configuration databases, hardware testbeds, software testbeds, etc.